

# Combinatorial Problems in Scientific Computing

Introduction

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Informatik 12:  
Software and Tools for Computational Engineering (STCE)

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## Motivation

Newton's Method

SuiteSparse Matrix Collection

## Admin

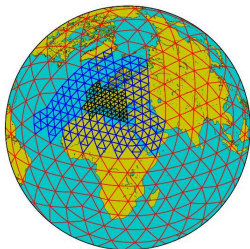
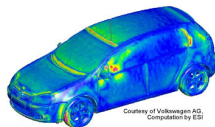
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**Scientific computing** uses mathematical modelling to numerically simulate / predict / optimize reality, e.g. automotive engineering, geophysics, ...



**Numerical simulations** are implemented as computer programs.

**Sparsity** is induced by missing data dependences, e.g. today's temperature in Hong Kong is probably independent of yesterday's temperature in Aachen, ...

Numerical programs exhibit **structure**, e.g. iteration, recursion, ...

Efficiency and robustness requires solution of various combinatorial problems (ordering, coloring, elimination, ...) on sparse matrices and graphs.

Key ingredients of scientific computing are the numerical approximation of solutions of

- ▶ systems of nonlinear equations

$$F(x) = 0, \quad F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

for given implementations of the **residual**  $y = F(x)$  and

- ▶ convex unconstrained nonlinear optimization problems

$$\operatorname{argmin}_x f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}$$

for given implementations of the **objective**  $y = f(x)$

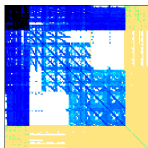
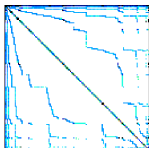
by Newton's method. The method uses differentiation and linear algebra  $\Rightarrow$  plenty of structure and sparsity to exploit.

The content of this course inspired by the ingredients of Newton's method, namely

- ▶ solution of **systems of linear equations** involving
  - ▶ sparse matrix-vector products
  - ▶ sparse matrix chain products
  - ▶ sparse direct linear solvers
- ▶ **algorithmic differentiation** involving
  - ▶ accumulation of sparse Jacobians and Hessians
  - ▶ data-flow reversal

The discussion of these topics will be based on introductions to essential background of Newton's method and of algorithmic differentiation.

We use generic residuals  $F(x)[= 0]$  and objectives  $[\min_x]f(x)$  replicating given sparsity patterns, e.g., provided by the SuiteSparse Matrix Collection; see [sparse.tamu.edu](http://sparse.tamu.edu).



... not a virus!

A dense matrix has  $n^2$  nonzero entries (obviously, ...).

A matrix is **sparse** if the number of nonzero entries is  $O(n)$ .

Consider linear system  $A \cdot x = b$  with regular system matrix  $A \in \mathbb{R}^{n \times n}$  and solved as

$$L \cdot \underbrace{U \cdot x}_{:=z} = b$$

by

- ▶  $A = L \cdot U$  decomposition at cost of  $O(n^3)$
- ▶ forward substitution for  $L \cdot z = b$  at cost of  $O(n^2)$
- ▶ backward substitution for  $U \cdot x = z$  at cost of  $O(n^2)$

Obviously, treatment of a lower triangular  $A$  as dense, e.g.,

$$\begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}$$

is suboptimal.



Householder Reflection of  $\mathbf{a} \in \mathbb{R}^n$  :

$$\mathbf{v} = \mathbf{a} + \text{sign}(a_0) \cdot \|\mathbf{a}\| \cdot \mathbf{e}_0$$

$$H = I - 2 \cdot \frac{\mathbf{v} \cdot \mathbf{v}^T}{\mathbf{v}^T \cdot \mathbf{v}}$$

$$\mathbf{a} = H \cdot \mathbf{a}$$

better at cost of  $O(n)$  (instead of  $O(n^2)$ )

$$\mathbf{v} = \mathbf{a} + \text{sign}(a_0) \cdot \|\mathbf{a}\| \cdot \mathbf{e}_0$$

$$\mathbf{a} = \mathbf{a} - 2 \cdot \frac{\mathbf{v}^T \cdot \mathbf{a}}{\mathbf{v}^T \cdot \mathbf{v}} \cdot \mathbf{v}$$

- ▶ associativity of matrix multiplication

$$\left( \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \right) \cdot \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \left( \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 3 \end{pmatrix} \right)$$

- ▶ distributivity of real arithmetic

$$a_1 \cdot b_1 \cdot c \cdot d + a_2 \cdot b_2 \cdot c \cdot d = (a_1 \cdot b_1 + a_2 \cdot b_2) \cdot c \cdot d$$

- ▶ structural orthogonality of vectors

$$\left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \right) \cdot 3$$

carries same information as

$$\left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cdot 3, \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cdot 3 \right)$$

in less storage (and potentially at lower computational cost).

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## Further Details on RWTH Moodle

- ▶ The **lecture** covers general story including theory and algorithms (videos + Q&A via Zoom).
- ▶ The **tutorial** (via Zoom) supports the lecture by discussing both pen&paper as well as programming exercises → **bonus credits**
- ▶ **Learning material** consists of videos, slides, code, reference solutions for tutorial exercises, pointers into literature, e.g, ...
- ▶ **Registration** (RWTH online) “buys” you access to the RWTH Moodle page of the course.



You can earn up to two bonus credits for submission of **reasonable** solutions to

- ▶ 60% (single credit)
- ▶ 80% (two credits)

of the tutorial exercises.

A single credit improves your final grade ( $\leq 4.0$ ) by one level (e.g. from 1.7 to 1.3).

- ▶ Scientific computing is an essential element of mankind's toolbox for understanding the world.
- ▶ Combinatorial problems occur in the context of many scientific computing methods.
- ▶ For example, they can be posed as ordering, coloring or elimination problems on sparse matrices and/or graphs.
- ▶ Knowledge of algorithms for the solution of these problems enables efficient and robust implementation of numerical simulation methods.
- ▶ You should attend this course ... ;-)